

Then every matrix (with real entries) has a singular value decomposition: $M = U \Sigma V^T$

Annotations: Σ is diagonal (center), U and V are orthogonal matrices.

(Σ has the same shape as M , so may not be square.)
 (But if $\Sigma = (\sigma_{ij})$, then $\sigma_{ij} = 0$ when $i \neq j$)

Remark: there's a version which also works for matrices w/ complex entries.

Calculator interface showing the SVD of $M = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}$.
 Result: $M = U \cdot \Sigma \cdot V^T$
 where $M = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}$
 $U = \begin{pmatrix} 0.229848 & 0.883461 & 0.408248 \\ 0.524745 & 0.240782 & -0.816497 \\ 0.819642 & -0.401896 & 0.408248 \end{pmatrix}$
 $\Sigma = \begin{pmatrix} 9.52552 & 0 \\ 0 & 0.514301 \\ 0 & 0 \end{pmatrix}$
 $V = \begin{pmatrix} 0.619629 & -0.784894 \\ 0.784894 & 0.619629 \end{pmatrix}$

Handwritten equation: $\begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix} = \begin{pmatrix} 0.22 & & \\ & 0.52 & \\ & & 0.81 \end{pmatrix} \cdot \begin{pmatrix} 0.6 & \\ & -0.7 \end{pmatrix}$

Annotations: "left singular vectors" (pointing to the first column of U), "right sing. vects" (pointing to the first column of V).

Annotations: "singular values" (pointing to the diagonal elements of Sigma), $\sigma_1 \geq \sigma_2 \geq \dots \geq 0$.

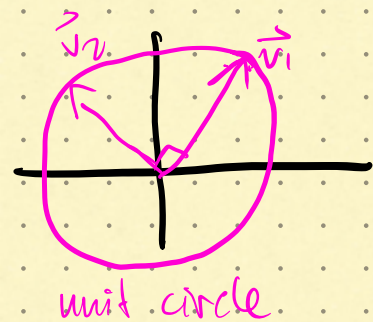
Why do we care?

Geometrically:

eg. $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \approx \begin{pmatrix} 0.4 & 0.9 \\ 0.9 & -0.4 \end{pmatrix} \begin{pmatrix} 5 & 0 \\ 0 & 0.3 \end{pmatrix} \begin{pmatrix} 0.6 & 0.8 \\ -0.8 & 0.6 \end{pmatrix}$

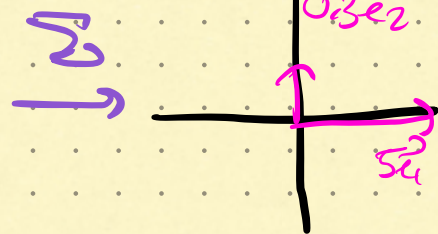
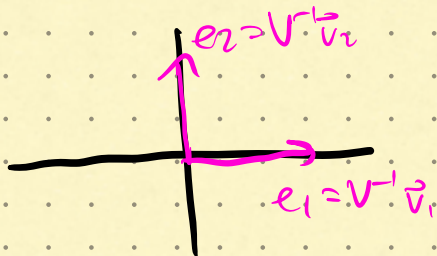
Annotations: $\leftarrow v_1^T$ (pointing to the first column of the third matrix), $\leftarrow v_2^T$ (pointing to the second column of the third matrix).

$$U = \begin{bmatrix} u_1 & u_2 \end{bmatrix} \quad \Sigma = \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix} \quad V^T = \begin{bmatrix} v_1 & v_2 \end{bmatrix}$$

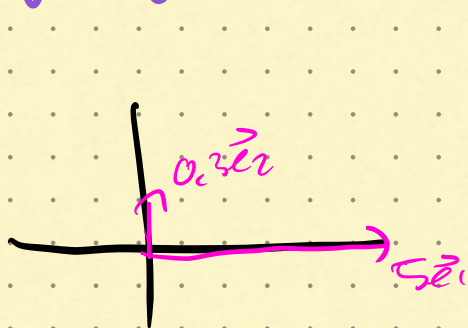


$$V^T = V^{-1}$$

rotate

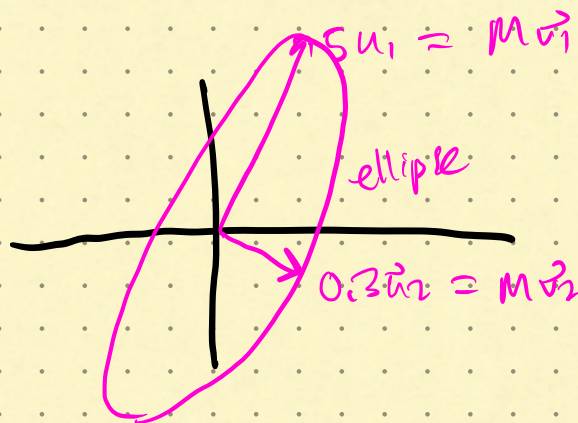


$$V^{-1} V = I_2 \rightsquigarrow V^{-1} [v_1 \ v_2] = [e_1 \ e_2]$$



$$U$$

rotate / flip



So: any linear transform is a combination of rotations/flips and scalings.

- left singular vectors give us axes of the ellipse where M sends the unit circle.

How do we compute SVD?

$$\text{let } A = U \Sigma V^T$$

↑ ↑ ↑
unknown

(Recall: U, V orthogonal,
 Σ "almost" diagonal)

Then $A^T A = (U \Sigma V^T)^T U \Sigma V^T$

$\Sigma = \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \\ 0 & 0 \end{pmatrix}$

$\Sigma^T = \begin{pmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \end{pmatrix}$

$= (V^T)^T \Sigma^T U^T \cdot U \Sigma V^T$

$U^T U = I$

$= V \underbrace{\Sigma^T \Sigma}_{\text{diagonal matrix!}} V^T$ diagonalizable.

symmetric \nearrow

eg. $\begin{pmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \end{pmatrix} \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix} = \begin{pmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{pmatrix}$

This is a diagonalization of $A^T A$!

\Rightarrow the columns of V are eigenvectors of $A^T A$!

The eigenvalues of $A^T A$ are the numbers σ_i^2 , where σ_i are the nonzero entries of Σ (singular values of A).

What about U ?

• one approach: a similar calculation shows that cols of U are eigenvectors of AA^T (caution)

• another approach: $A \vec{v}_i = \sigma_i u_i$, solve for \vec{u}_i

using the σ_i and \vec{v}_i we already found.